



QM, Dec 23, 2002

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Constrained Optimization

- Again we want to find $\max_{x \in S} f(x)$ or

$\min_{x \in S} f(x)$ for some function $f: \mathbb{R}^n \rightarrow \mathbb{R}$

- Here we have some constraints:

$$g_1(x) = 0, \dots, g_M(x) = 0 \quad (\text{equalities})$$

$$h_1(x) \geq 0, \dots, h_p(x) \geq 0 \quad (\text{inequalities})$$

Equality-Constrained Optimization:

Lagrange Method.

Theorem: If x^* is a local optimum, and

$$\text{rank} \begin{bmatrix} \frac{\partial g_1}{\partial x_1}(x^*) & \dots & \frac{\partial g_1}{\partial x_n}(x^*) \\ \vdots & & \vdots \\ \frac{\partial g_M}{\partial x_1}(x^*) & \dots & \frac{\partial g_M}{\partial x_n}(x^*) \end{bmatrix} = M, \text{ then there}$$

exists a vector $\lambda^* = \begin{bmatrix} \lambda_1^* \\ \vdots \\ \lambda_M^* \end{bmatrix} \in \mathbb{R}^M$ such

$$\text{that } \frac{\partial f}{\partial x_i}(x^*) + \sum_{j=1}^M \lambda_j^* \frac{\partial g_j}{\partial x_i}(x^*) = 0. \quad (i=1, \dots, n)$$



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- This is equivalent to finding max or min of the Lagrangian:

$$L = f + \sum_{j=1}^M \lambda_j g_j : \frac{\partial L}{\partial x_i} = 0 \quad \text{and} \quad \frac{\partial L}{\partial \lambda_j} = 0$$

constraint

- Additional conditions (maximality or minimality) are the same as in unconstrained case for f , i.e. we need to investigate definiteness of Hessian matrix for L

- Be aware that $\text{rank} \left[\frac{\partial f_j}{\partial x_i}(x^*) \right]$ must be equal to number of constraints M ! If not, this procedure will not work, although max or min can exist.

- Example: $f(x,y) = x^2 - y^2$, $g(x,y) = 1 - x^2 - y^2$

$$L = f(x,y) + \lambda g(x,y) = x^2 - y^2 + \lambda (1 - x^2 - y^2)$$



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$$\frac{\partial L}{\partial x} = 2x - 2\lambda x = 0 \Rightarrow x^*(1 - \lambda^*) = 0$$

$$\frac{\partial L}{\partial y} = -2y - 2y\lambda = 0 \Rightarrow y^*(1 + \lambda^*) = 0$$

$$\frac{\partial L}{\partial \lambda} = 1 - x^2 - y^2 = 0 \Rightarrow x^{*2} + y^{*2} = 1$$

If $x^* = 0$, from the third equation follows
 $y^* = \pm 1$, and from the second $\lambda^* = -1$,
so we have two solutions $(x^*, y^*, \lambda^*) = (0, \pm 1, -1)$

If $x^* \neq 0$, then $\lambda^* = 1$ from the first,
and $y^* = 0$ from the second equation.

From the third equation we have

$x^* = \pm 1$, so we have two additional
solutions: $(\pm 1, 0, 1)$.

$\text{rank} \left[\frac{\partial f_i}{\partial x_i} \right] = \text{rank} \begin{bmatrix} -2x^* & -2y^* \end{bmatrix}$, so for the
first solution we have



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$$\text{rank} \left[\frac{\partial^2 f}{\partial x_i^2} \right] = \text{rank} [0 \quad \mp 2] = 1 = M,$$

so all conditions for the theorem are satisfied.

For the second pair i 's

$$\text{rank} \left[\frac{\partial^2 f}{\partial x_i^2} \right] = \text{rank} [\mp 2 \quad 0] = 1 = M,$$

so everything is OK here also.

- Hessian matrix is

$$H = \begin{bmatrix} 2-2\lambda & 0 \\ 0 & -2-2\lambda \end{bmatrix}$$

For $(0, \pm 1, -1)$ is $H = \begin{bmatrix} 4 & 0 \\ 0 & 0 \end{bmatrix} \geq 0$

For $(\pm 1, 0, 1)$ is $H = \begin{bmatrix} 0 & 0 \\ 0 & 4 \end{bmatrix} \geq 0$

All solutions are minimums, although not strict ones.



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Inequality-Constrained Optimization:
Kuhn-Tucker Method

Theorem: If x^* is a local maximum,
and $\text{rank} \left[\frac{\partial h_{Ej}}{\partial x_i} \right] = M_E$, where h_E are
constraints with the equality sign valid for
 x^* , and M_E is the number of those
constraints; then there exists a vector
 $\lambda^* = \begin{bmatrix} \lambda_1^* \\ \vdots \\ \lambda_N^* \end{bmatrix} \in \mathbb{R}^N$ such that

$$\frac{\partial f}{\partial x_i}(x^*) + \sum_{j=1}^N \lambda_j^* \frac{\partial h_j}{\partial x_i}(x^*) = 0 \quad (i=1, \dots, n)$$

$$h_i(x^*) \geq 0$$

$$\lambda_i^* \geq 0$$

$$\lambda_i^* h_i(x^*) = 0.$$

— Note that you need to transform the
problem of optimization into the



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maximization problem with all conditions of the form $h_i(x^*) \geq 0$, which can easily be done.

- We can again construct Lagrangian

$$L = f + \sum_{j=1}^N \lambda_j h_j,$$

and the equations for x^* are

$$\frac{\partial L}{\partial x_i} = 0, \quad \frac{\partial L}{\partial \lambda_j} \geq 0, \quad \lambda_j^* \geq 0$$

$$\lambda_j^* h_j(x^*) = 0.$$

- Be aware of the problems with rank!

- Example: $f(x, y) = x + y$, $h(x, y) = xy - 1$

$$L = f + \lambda h = x + y + \lambda(xy - 1)$$

$$\frac{\partial L}{\partial x} = 1 + \lambda y = 0 \Rightarrow \lambda^* y^* = -1 \Rightarrow \lambda^* \neq 0, y^* \neq 0$$

$$\frac{\partial L}{\partial y} = 1 + \lambda x = 0 \Rightarrow \lambda^* x^* = -1 \Rightarrow \lambda^* \neq 0, x^* \neq 0$$



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$$y^* = x^* = -\frac{1}{\lambda^*}$$

$$\frac{\partial \mathcal{L}}{\partial x} = xy - 1 \geq 0, \quad \lambda^* \geq 0, \quad \lambda^*(x^*y^* - 1) = 0$$

0 >

$$x^*y^* - 1 = \frac{1}{\lambda^{*2}} - 1 \geq 0 \Rightarrow \lambda^{*2} \leq 1$$

$$\text{with } \lambda^* \geq 0 \Rightarrow 0 \leq \lambda^* \leq 1$$

Since $\lambda^* \neq 0$, we have $x^*y^* = 1 \Rightarrow \lambda^* = 1$,

$x^* = y^* = -1$, so the solution is $(-1, -1, 1)$.

$$\text{rank} \left[\frac{\partial h_{E2}}{\partial x_i}(x^*) \right] = [x^* \ y^*] = [-1 \ -1] = 1,$$

So the conditions are OK.

- For homework you can check if this x 's a maximum or not (it cannot be a minimum!)

- For the definition and introduction to the Markowitz problem, you can consult lecture notes from Jan 9, 2004, or ch. 6 of "Investment Science" by D. Luenberger



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Homework problems for constrained optimization:

1) $f(x,y) = x^2 - y^2$, $g(x,y) = 1 - x - y$

2) $f(x,y) = \frac{x^3}{3} - \frac{3y^2}{2} + 2x$, $g(x,y) = x - y$

} equality
const.

3) $f(x,y) = x^2 - y$, $h(x,y) = 1 - x^2 - y^2$

4) $f(x,y) = 2x^3 - 3x^2$, $h(x,y) = (3-x)^3$

5) $f(x,y) = x^2 - x$, $h(x,y) = x$

} inequality
constrained



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Economic Example: Markowitz Problem

If we have n assets with expected rates of return $\bar{r}_1, \dots, \bar{r}_n$ and the covariances σ_{ij} , ($i, j = 1, \dots, n$), a portfolio is defined by a set of n weights w_i , $i = 1, \dots, n$, so that $\sum_{i=1}^n w_i = 1$. The problem is to

$$\text{minimize } \frac{1}{2} \sum_{i,j=1}^n w_i w_j \sigma_{ij},$$

subject to constraints:

$$\sum_{i=1}^n w_i \bar{r}_i = \bar{r}, \quad \sum_{i=1}^n w_i = 1.$$

- Lagrangian is

$$L = \frac{1}{2} \sum_{i,j=1}^n w_i w_j \sigma_{ij} + \lambda \left(\sum_{i=1}^n w_i \bar{r}_i - \bar{r} \right) + \mu \left(\sum_{i=1}^n w_i - 1 \right)$$

- To simplify things, we will work with $n=2$, so that

$$L = \frac{1}{2}(w_1^2 \sigma_1^2 + w_1 w_2 \sigma_{12} + w_2 w_1 \sigma_{21} + w_2^2 \sigma_2^2) + \lambda (w_1 \bar{r}_1 + w_2 \bar{r}_2 - \bar{r}) + \mu (w_1 + w_2 - 1)$$

- The equations are

$$\frac{\partial L}{\partial w_1} = w_1 \sigma_1^2 + \frac{1}{2} w_2 \sigma_{12} + \frac{1}{2} w_2 \sigma_{21} + \lambda \bar{r}_1 + \mu = 0$$

$$\frac{\partial L}{\partial w_2} = \frac{1}{2} w_1 \sigma_{12} + \frac{1}{2} w_1 \sigma_{21} + w_2 \sigma_2^2 + \lambda \bar{r}_2 + \mu = 0$$

$$\frac{\partial L}{\partial \lambda} = w_1 \bar{r}_1 + w_2 \bar{r}_2 - \bar{r} = 0$$

$$\frac{\partial L}{\partial \mu} = w_1 + w_2 - 1 = 0$$

- Since $\sigma_{12} = \sigma_{21}$, we have a set of 4 equations in 4 unknowns w_1, w_2, λ , and μ :

$$w_1 \sigma_1^2 + w_2 \sigma_{12} + \lambda \bar{r}_1 + \mu = 0$$

$$w_2 \sigma_{12} + w_2 \sigma_2^2 + \lambda \bar{r}_2 + \mu = 0$$

$$w_1 \bar{r}_1 + w_2 \bar{r}_2 = \bar{r}$$

$$w_1 + w_2 = 1$$



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- And now we have a system of linear equations, which can be easily solved

- General set of equations is

$$\sum_{j=1}^n \sigma_{ij} w_j + \lambda \bar{r}_i + \mu = 0 \quad (i=1, \dots, n)$$

$$\sum_{i=1}^n w_i \bar{r}_i = \bar{r}$$

$$\sum_{i=1}^n w_i = 1$$

- we have system of $n+2$ ~~unknowns~~ equations in $n+2$ unknowns (w_i, λ, μ).

→ Homework Problem: Solve the Markowitz problem for a set of three uncorrelated assets, with $\sigma_1^2 = 1$, $\sigma_2^2 = 4$, $\sigma_3^2 = 9$, and $\bar{r}_1 = 1$, $\bar{r}_2 = 2$, $\bar{r}_3 = 3$.



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- Solutions of Homework problems assigned
on Dec 22, 2004.

$$1) f(x) = x^2 + x^3, \quad f'(x) = 2x + 3x^2 = x(2+3x)$$

$$f'(x) = 0 \Leftrightarrow x(2+3x) = 0 \Leftrightarrow x = 0 \vee x = -\frac{2}{3}$$

If $x^* = 0$, then $f''(x) = 2 + 6x$ is
at x^* equal to $f''(0) = 2 > 0$, so

$x^* = 0$ is minimum.

If $x^* = -\frac{2}{3}$, then $f''(x^*) = f''(-\frac{2}{3}) = 2 + 6 \cdot (-\frac{2}{3}) =$
 $= 2 - 4 = -2 < 0$, so $x^* = -\frac{2}{3}$ is maximum.

$$2) f(x) = e^x \sin x, \quad f'(x) = e^x \sin x + e^x \cos x$$

$$f''(x) = \cancel{e^x \sin x} + e^x \cos x + e^x \cos x - \cancel{e^x \sin x} =$$
$$= 2e^x \cos x$$

$$f'(x) = 0 \Leftrightarrow e^x (\sin x + \cos x) = 0$$



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- Since $e^x > 0$, the condition for x^* is
 $\sin x + \cos x = 0$

- Using mathematical identities
 $\cos x = \sin(\frac{\pi}{2} - x) = -\sin(x - \frac{\pi}{2})$ and
 $\sin(\alpha \pm \beta) = \sin \alpha \cos \beta \pm \cos \alpha \sin \beta$, we can
transform this equation into

$$\begin{aligned} \sin x + \cos x &= \sin(x - \frac{\pi}{4} + \frac{\pi}{4}) - \sin(x - \frac{\pi}{4} - \frac{\pi}{4}) = \\ &= \sin(x - \frac{\pi}{4}) \cos \frac{\pi}{4} + \cos(x - \frac{\pi}{4}) \sin \frac{\pi}{4} - \\ &\quad - \sin(x - \frac{\pi}{4}) \cos \frac{\pi}{4} + \cos(x - \frac{\pi}{4}) \sin \frac{\pi}{4} = \\ &= 2 \sin \frac{\pi}{4} \cos(x - \frac{\pi}{4}) = 0 \Rightarrow \end{aligned}$$

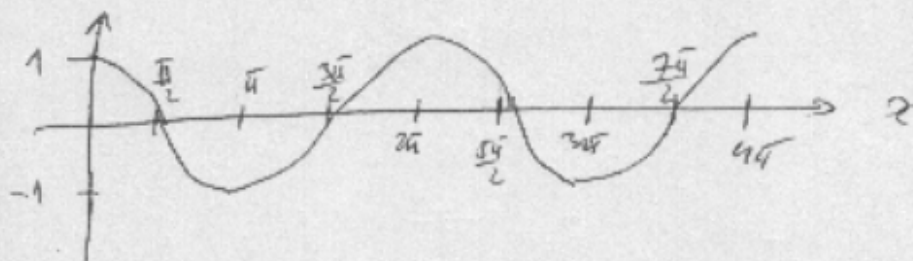
$$x - \frac{\pi}{4} = \frac{\pi}{2} + k\pi, \quad k \in \mathbb{Z}, \quad \text{so}$$

we have $x_k^* = \frac{3\pi}{4} + k\pi$

$$f''(x_k^*) = 2 e^{x_k^*} \cos x_k^* = 2 e^{\frac{3\pi}{4} + k\pi} \cos(\frac{3\pi}{4} + k\pi)$$

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From the graph of cos function



we can see that

$$\cos\left(\frac{3\pi}{4}\right) < 0, \quad \cos\left(\frac{3\pi}{4} + \pi\right) \geq 0,$$

$$\cos\left(\frac{3\pi}{4} + 2\pi\right) < 0, \quad \dots, \quad \text{so}$$

$$\cos\left(\frac{3\pi}{4} + k\pi\right) \begin{cases} < 0 & \text{for } k \text{ even} \\ > 0 & \text{for } k \text{ odd, and} \end{cases}$$

$$x_k^* = \frac{3\pi}{4} + k\pi \begin{cases} \text{is maximum} & \text{for } k \text{ even} \\ \text{is minimum} & \text{for } k \text{ odd} \end{cases}$$

$$3) f(x, y) = x^4 y^2 + x^2 y^4 - 2x^2 y^2$$

$$\frac{\partial f}{\partial x} = 4x^3 y^2 + 2x y^4 - 2x y^2 = 0$$

$$\frac{\partial f}{\partial y} = 2x^4 y + 4x^2 y^3 - 2x^2 y = 0$$

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If $x=0$, then both eq. are satisfied.

If $y=0$, again both eq. are satisfied.

So, we have solutions $(0, y)$, $(x, 0)$,
where x, y are free parameters.

If $x \neq 0$ and $y \neq 0$ we can divide first
eq. by xy^2 and second eq. by x^2y :

$$\frac{1}{2}x^2 + 2y^2 = 2 \quad /:2 \qquad 2x^2 + y^2 = 1$$

$$2x^2 + 4y^2 = 2 \quad /:2 \qquad x^2 + 2y^2 = 1$$

The unique solution of this system of linear
equation in x^2, y^2 is $x^2 = y^2 = \frac{1}{3}$, so we
have for solutions (two pairs)

$$\left(\pm \frac{1}{\sqrt{3}}, \pm \frac{1}{\sqrt{3}}\right) \text{ and } \left(\pm \frac{1}{\sqrt{3}}, \mp \frac{1}{\sqrt{3}}\right).$$

Hessian matrix is

$$H = \begin{bmatrix} 12x^2y^2 + 2y^4 - 2y^2 & 8x^3y + 8xy^3 - 4xy \\ 8x^3y + 8xy^3 - 4xy & 2x^4 + 12x^2y^2 - 2x^2 \end{bmatrix}$$



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- For the solution $(0, y)$, we have

$$H = \begin{bmatrix} 2y^4 - 2y^2 & 0 \\ 0 & 0 \end{bmatrix}$$

This matrix is positive semidefinite for $y^2 > 1$, and negative semidefinite for

$$0 < y^2 < 1.$$

- For the solution $(x, 0)$, we have

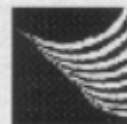
$$H = \begin{bmatrix} 0 & 0 \\ 0 & 2x^4 - 2x^2 \end{bmatrix},$$

and the answer is the same as in the previous case.

To be sure if these points are minima or maxima, we need further investigation.

- For $(\pm \frac{1}{\sqrt{3}}, \pm \frac{1}{\sqrt{3}})$ we have

$$H = \begin{bmatrix} \frac{12}{9} + \frac{2}{9} - \frac{2}{3} & \frac{8}{9} + \frac{8}{9} - \frac{4}{3} \\ \frac{8}{9} + \frac{8}{9} - \frac{4}{3} & \frac{2}{9} + \frac{12}{9} - \frac{2}{3} \end{bmatrix} = \begin{bmatrix} \frac{8}{9} & \frac{4}{9} \\ \frac{4}{9} & \frac{8}{9} \end{bmatrix}$$



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$$H_{11} > 0, \quad \det H = \left(\frac{8}{9}\right)^2 - \left(\frac{4}{9}\right)^2 > 0 \Rightarrow$$

H is positive definite $\Rightarrow \left(\pm \frac{1}{\sqrt{3}}, \pm \frac{1}{\sqrt{3}}\right)$ is minimum.

For $\left(\pm \frac{1}{\sqrt{3}}, \mp \frac{1}{\sqrt{3}}\right)$ we have

$$H = \begin{bmatrix} \frac{12}{9} + \frac{2}{9} - \frac{2}{3} & -\frac{8}{9} - \frac{8}{9} + \frac{4}{3} \\ -\frac{8}{9} - \frac{8}{9} + \frac{4}{3} & \frac{2}{9} + \frac{12}{9} - \frac{2}{3} \end{bmatrix} = \begin{bmatrix} \frac{8}{9} & -\frac{4}{9} \\ -\frac{4}{9} & \frac{8}{9} \end{bmatrix}$$

$$H_{11} > 0, \quad \det H = \left(\frac{8}{9}\right)^2 - \left(-\frac{4}{9}\right)^2 > 0, \quad \text{so}$$

H is positive definite $\Rightarrow \left(\pm \frac{1}{\sqrt{3}}, \mp \frac{1}{\sqrt{3}}\right)$ is minimum.

$$4) \quad f(x, y, z) = 2x^2 + 2y^2 + 2z^2 + 2xy + 2xz + 2yz$$

$$\frac{\partial f}{\partial x} = 4x + 2y + 2z = 0$$

$$\frac{\partial f}{\partial y} = 4y + 2x + 2z = 0$$

$$\frac{\partial f}{\partial z} = 4z + 2x + 2y = 0$$



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The determinant of this system is

$$\det \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix} = 4 \begin{vmatrix} 4 & 2 \\ 2 & 4 \end{vmatrix} - 2 \begin{vmatrix} 2 & 2 \\ 2 & 4 \end{vmatrix} + 2 \begin{vmatrix} 2 & 2 \\ 4 & 2 \end{vmatrix} =$$
$$= 4 \cdot (16 - 4) - 2 \cdot (8 - 4) + 2 \cdot (4 - 8) =$$
$$= 48 - 8 - 8 = 32 \neq 0$$

Since the system is homogeneous, it has a unique solution $x^* = y^* = z^* = 0$.

Hessian matrix is

$$H = \begin{bmatrix} 4 & 2 & 2 \\ 2 & 4 & 2 \\ 2 & 2 & 4 \end{bmatrix},$$

the same as the matrix of the above solved system.

$$H_{11} > 0, \quad \begin{vmatrix} H_{11} & H_{12} \\ H_{21} & H_{22} \end{vmatrix} = \begin{vmatrix} 4 & 2 \\ 2 & 4 \end{vmatrix} = 16 - 4 = 12 > 0,$$

$\det H = 32 > 0 \Rightarrow H$ is positive definite,

and $x^* = y^* = z^* = 0$ is minimum of f .